

MF 9700 QUINARY

User Manual



User manual for MF 9700 QUINARY, the most comprehensive and latest device for the detection and exploration of underground water, precious metals, voids and caves. Six different operating systems for search and exploration.

SHOP DETECTORS

TEL : +1 206-401-9788

WEB : <https://shopdetectors.com/>

EMAIL : contact@shopdetectors.com

WWW.MWF-USA.COM



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The operating in high voltage areas would limit the results and performance



The cell signal interferes with the device signal, so turn off the cell while operating



Don't operate two devices with same method of search at the same place



Don't store in high temperature or high humidity



Disconnect the batteries before long time storage



The operator Must remove any metals that might affect the opeartin e.g.: Rings, watch, belt....



Any attempt to tamper the device or unapproved maintenance would void the warranty



For devices that work on replaceable batteries, use good quality batteries to work longer hours.



- ❖ The user must practice before starting the detecting operations and discoveries
- ❖ Store in Cool and dry place 15-40 C 5%-75% humidity



Read & Understand
The User's manual
before using this device

Search System:

Multiple Search Systems:

- 1- Long Range Locator (Hand-held)
- 2- Long Range Locator (Line Tracking)
- 3- iON Sense
- 4- Ground Sense
- 5- Geophysical
- 6- Ground Scan

Search Principle:

- 1- Digital Frequency Signal Processing (DFSP)
To receive the electrostatic fields of target.
- 2- Digital Frequency Signal Processing (DFSP)
To receive the electrostatic fields of target.
- 3- Processing the ionic levels in the field.
- 4- Magnetic fields sensing and evaluating
- 5- Scanning the ground layers by measuring the resistance and analysing the results.
- 6- Ground Scan and Imaging to contour targets underground.

Operating Processor:

MICROCONTLLER PIC18 & ARM 7

Operating Frequency:

- 1- From 1 KHz to 30 KHz
- 2- From 1 KHz to 30 KHz
- 3- 20.000 MHz
- 4- Magnetic Field Measurement
- 5- Electrical Resistance Measurement
- 6- Scan and Measuring Magnetic Field Intensity

Power Rating:

11.1 V / 6000 mAh

Power Consumption:

Max power @ 400mAh

Battery Endurance:	6 Working hours
Charger	4.2 V DC / 2 Amps
Display:	4.3" TFT LCD Display, 16 bit color depth CDMA GPU @ 48 MHz
Targets	Gold - Gold ore -Silver - Copper - Brass - Bronze - Iron - Groundwater - Voids and cavities - Gems
Target Discrimination:	YES
Selective Target Mode:	YES, selective target search mode or auto search for discovered targets
Search Depth	70 Mt with Selective Depth control system in the depth menu.
Search Distance:	2000 Mt with Selective Distance Control system in the distance menu.
Search Results:	<ol style="list-style-type: none"> 1- Signal and Guidance towards the target location 2- Signal and Guidance towards the target location 3-Visual data with digital information about the target size and location 4- Visual indicator (10 Bar-graph LED) and Sound Indicator 5-Visual and audio signals with indicators in addition to waveform for logging 6-Visual Data contouring the target location and size

Bluetooth:	NO
Wireless communications:	YES
Smart Auto guiding System:	YES
Audio notifications:	YES
Vibration notifications:	YES
Operating Temperature:	From (5° F) to (140° F) / From (-15 °C) to (40 °C)
Storing Temperature	From (5° F) to (140° F) / From (-15 °C) to (60 °C)
Humidity:	Store and operate within 90% humidity ratio
Weight:	7.75 Lbs (3.5Kg) with all the Accessories, 12.25 Lbs (5.5 Kg) for the case.
Dimensions:	10.5"x8"x3.5" (260X200X90 mm)
Case Dimensions:	mm 440X520X180

Main Unit

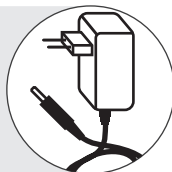
The Main Control Unit for the device to set the search and device parameters. Communicate with the other search systems via wireless link.



Charge Adapter

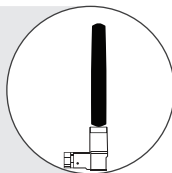
This charger is used to recharge the battery, make sure the power switch is on before starting the search or a screen would appear on the display prompting doing so.

Ratings: input 100-240v DC 50-60Hz 0.4A - Output:5v AC 3A 15W



Wireless Antenna

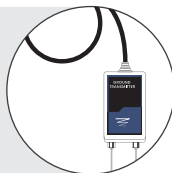
Antenna for boosting the signal for transmitting the data to the other search systems.



Ground Transmitter

Connect this unit to the Main unit and plant it in the ground to send the waves and reinforce the signal.

The ground transmitter should be connected for both systems to work.



Hand-held Unit

The LRL unit consist of the main unit, transceiver antenna, and the grip.

The unit runs on 4xAA batteries.



Line Tracker and Antennas

Connect the cable to the rods and the Line Receiver.

Use this unit with the Line Tracking search method.

The unit runs on a 9v battery.



Verification Unit and iON Sensor

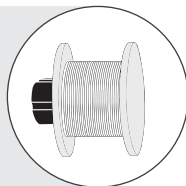
This unit is for detecting the ionic fields of the precious metals.

This unit is set by the Main Unit Wirelessly.



Four wire reels

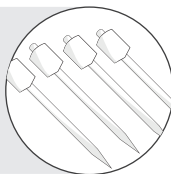
Four reels to ensure ease of use. High conductivity wires with excellent insulation. Connect these to the Power out connectors in the back of the Main Unit to Scan the area needed by the Geophysical System.



Four Stainless Steel Probes

Made of the best alloys to endure rust and environment conditions with high conductivity.

Plant these in the soil and connect them to the Main Unit to Measure the waves out of the device.



Ground Sensor

Connect to the Main Unit with the Ground Sensor System or Ground Scan System to Measure the magnetic levels of the ground to determine and locate targets. Equipped with high sensitivity sensors for best performance.



Headphones

Connect to the Main unit headphone jack or the Verification Unit.



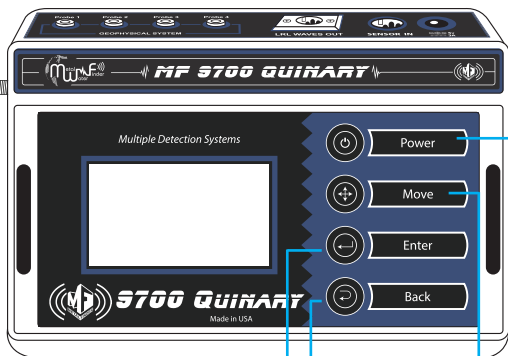
Main unit charger

This charger is used to recharge the battery, make sure the power switch is on before starting the search or a screen would appear on the display prompting doing so.

Ratings: input 100-240v DC 50-60Hz 0.4A - Output:13,5v AC 2A



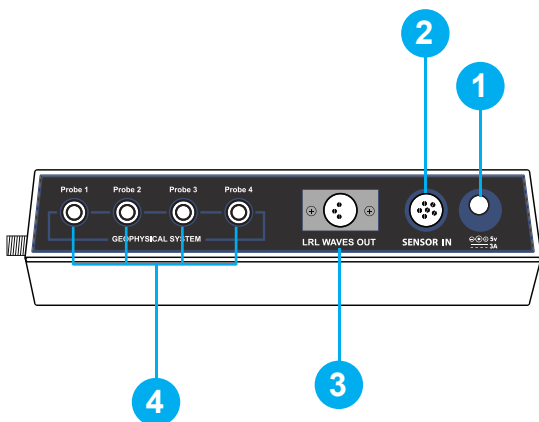
Front View



- 1 Headphone Jack
- 2 Power Button
- 3 Move Button

- 4 Enter button
- 5 Back Button
- 6 Wireless Antenna Connector

Back View



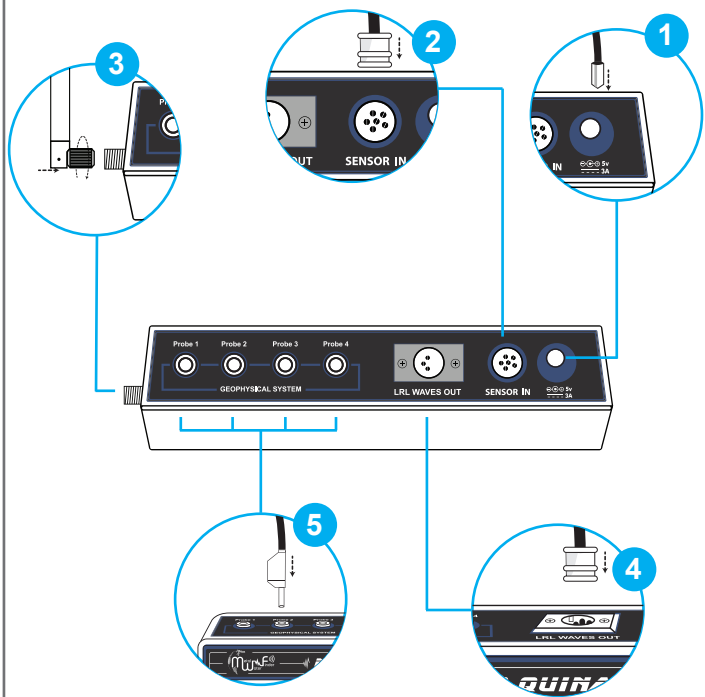
1 Charger Jack

2 Ground Sensor Connector

3 Ground Transmitter Connector

4 Electricity Power Output for Geo Scan

Assembly



- 1 Charging Connector.
- 2 Ground Sensor Connector. Connect the sensor when working with the Ground Sensor System or the Ground Scan System.
- 3 Wireless Antenna Connector.
- 4 Ground Transmitter Connector. Connect when using Long Range Locator system or Line Tracking.
- 5 Probes connectors. Connect the plugs to the connectors when using Geophysical System.

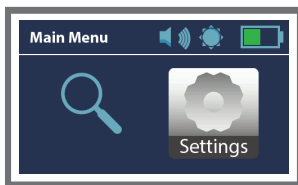
- ❖ Turn on the device by press and hold the power button in th front.
- ❖ The device will start and show a loading screens ,Then show the main menu.
- ❖ Note: The first run for the device you will be prompted to choose the system language.



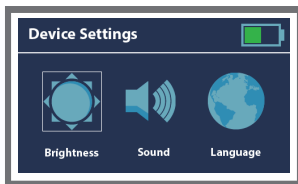
- ❖ Use the (Move) button to navigate through menus on the display and press (Enter) to select or confirm. Press (Back) to go to the previous Menu

❖ Settings Menu

To access the Settings Menu select the gear icon in the Main Menu and press (Enter) to the settings.

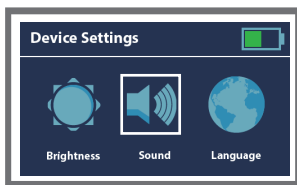


- To set the screen brightness select the icon and press(Enter) to change the brightness from 10% to 100%.

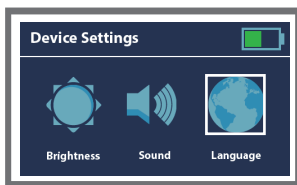


❖ Settings Menu

To set volume select the Speaker icon and press (Enter) to change the Volume from 1 to 5 or mute.



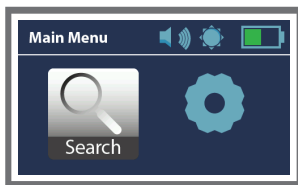
- To change the System language select and press(Enter) the device will load the language and display the menus in the designated language.



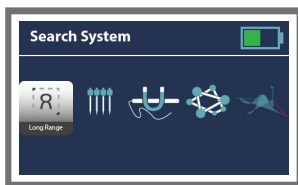
❖ Press (Back) to exit the Settings Menu and go back to the Main Menu.

Starting the Search

- To start the search process select the Search option from the Main Menu to access the search systems.

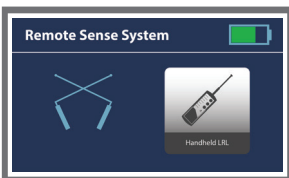


The search systems will appear on the display:
Select the Long Range System

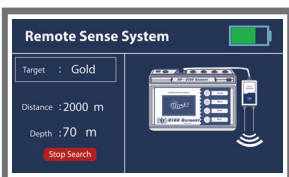


After selecting the Long Range System two options will appear on the screen (Line Tracking- Hand-held LRL)

These systems are the remote sensing methods.
Select a method to start with and press (Enter)



After selecting the search method the Search parameters interface will show.
Press(Move) to switch between the parameters and press(Enter) to change the values.



After selecting the search parameters (Target, Distance and Depth) Select start search and press (Enter) to start.



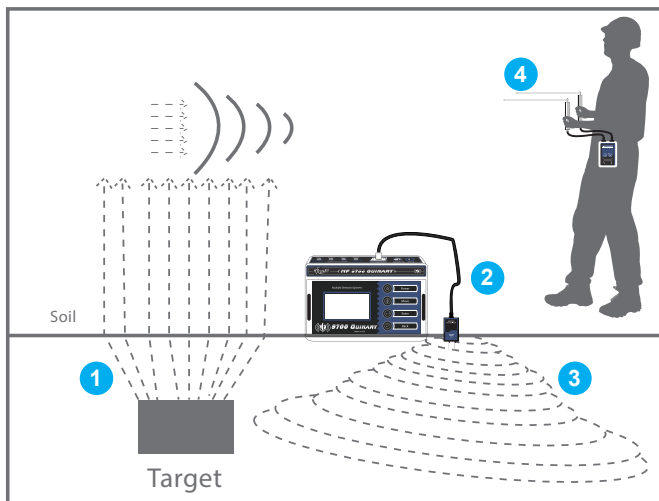
Note:

Make sure that the (Hand-held LRL) Unit or the (Line Tracker) is turned on and working before confirming the start of the search

Line Tracking

Line Tracker and Antennas

-
- 1 Power Switch**
Slide down to switch ON
Make sure the Tracker is off before storage.
- 2 Status LED**
Indicates the Line Tracker connectivity with the main unit.
Red = Disconnected
Green = Connected
- 3 Volume Button**
Press to change the volume or to mute the unit.
- 4 Speaker**
in the back of the Tracker
- 5 Battery Compartment**
To connect a 9VDC battery as shown in the figure below
- 6**
- 6** Connect the rods to the antennas then connect the unit in the top to the antennas by the attached cable.



- 1** The Target is affected by the earth electrostatic and magnetic fields
- 2** The tuning and transmitting unit transmits a electro-frequency waves to determine target location
- 3** The out waves spread through the earth which stimulate the formed fields around the target identify it and forming a power lines
- 4** The line Tracker device receives the power lines that connected to the target to determine the location

If you selected the Line Tracking search method, make sure that the Line Tracker is switched on and the indication LED is on then the Main Unit will send the start command to the Line Tracker with the selected parameters.

Note:

If there is Target, the device would form a frequency power line between the Target and the device.
If there is no target in the search area there would be no connection between the device waves and the selected target type.

Soil



Target
Location



If there is Target, power lines would be formed by the device and the target

Soil



If there is no target the device would not form any power lines

Then rotate around the ground transmitter unit

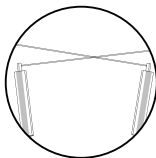
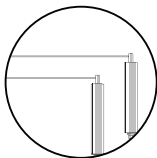
A- If there is target in the search area a signal will be received which represented by the intersecting of the antenna at some point which is the power line direction point between the device and the Target location.

B- but if the user rotates a full circle and no intersection happened, then the selected search target does not exist in the search area.



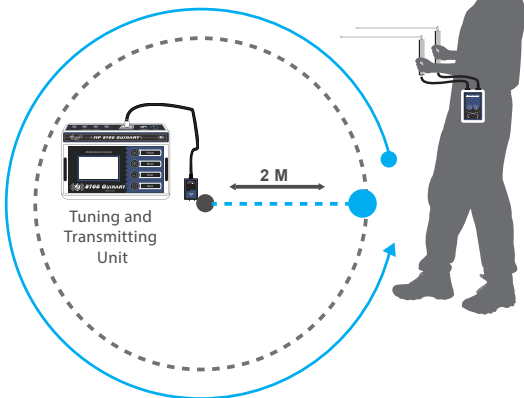
B

No Target Exists



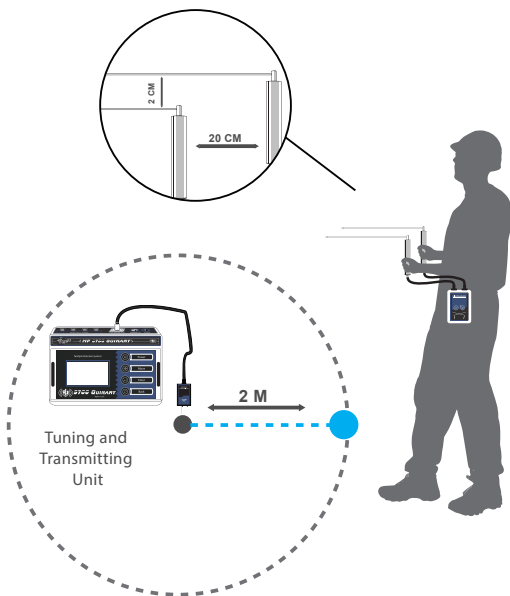
A

There is Target



How to locate Target (Stage one):

After setting and configuring the receiving device for search, fasten the Line Receiver Device on the belt or put it in pocket then measure a two meters distance from the ground transmitter unit which transmits the waves then hold the receiving antennas horizontally to the ground. hold an antenna in each hand with a 25 cm distance between and make sure that the right antenna is 2 cm above the left antenna as shown in figure



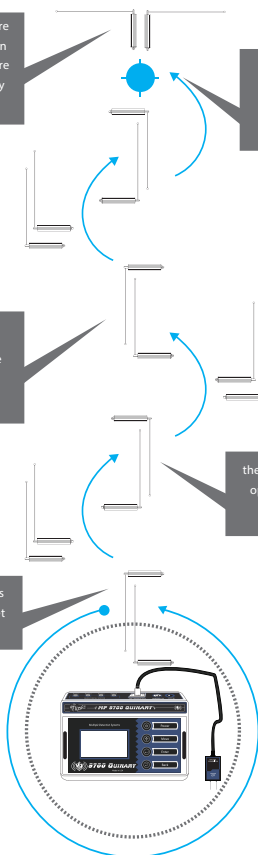
when passes the target point there will be no more intersecting again which means that the antennas are beyond the target point and they will turn back .

the midpoint between the last intersecting point and the first rotation point is the target point

walk and track the power line through the intersection of the antennas over the power line

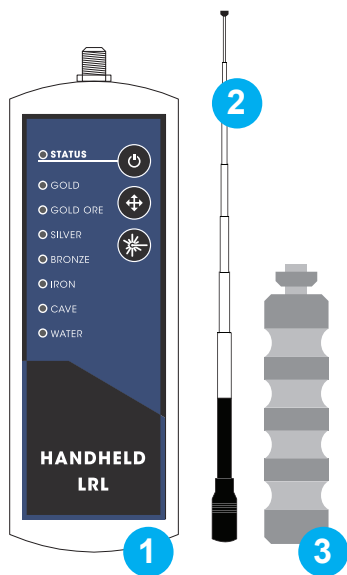
the antennas will get parallel and open when exit the power line

The antennas will intersect towards the power line leading to the Target location

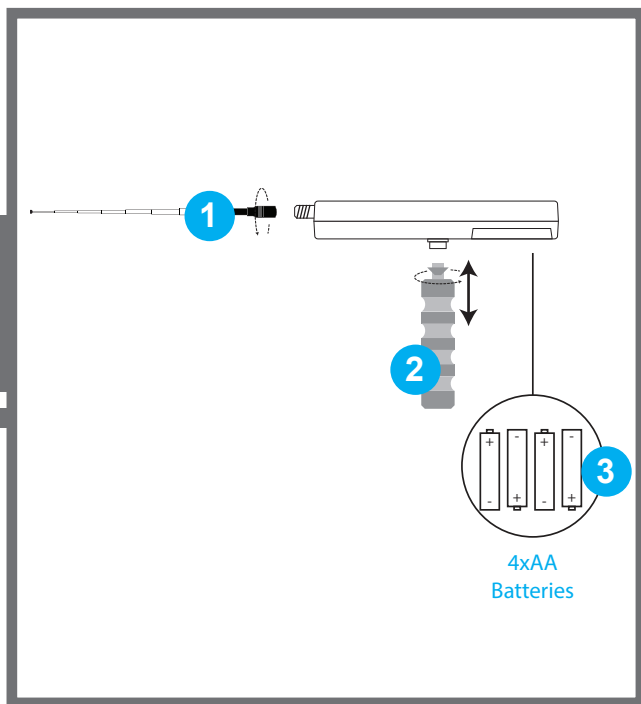


Rotate around the device with 2 meters radius

Hand-held Long
Range
Locator



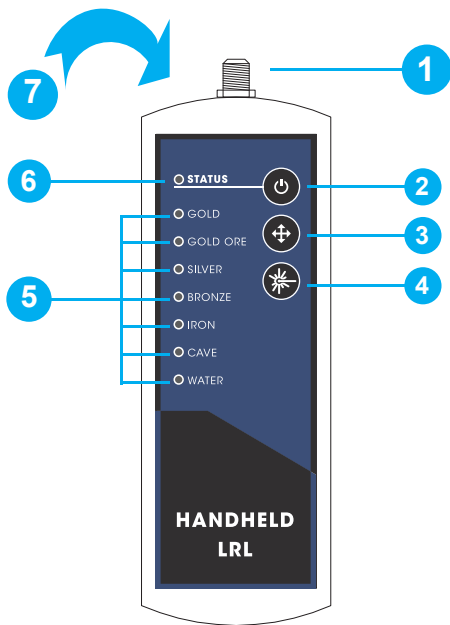
- 1** Hand-held LRL Unit
- 2** Transceiver Antenna
- 3** Handling Grip



- 1 Plug the antenna to the jack in front of the Handheld LRL Unit.
- 2 Connect the grip to the socket in the bottom of the Unit.
- 3 Put 4x AA Batteries in the battery compartment and pay attention to the polarity.

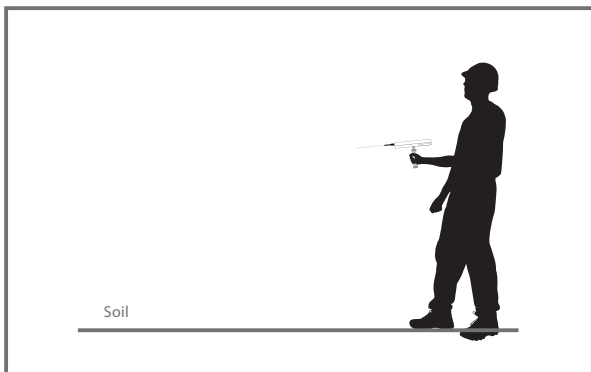
Note:

For the best product life use High quality batteries and remove them before storage.

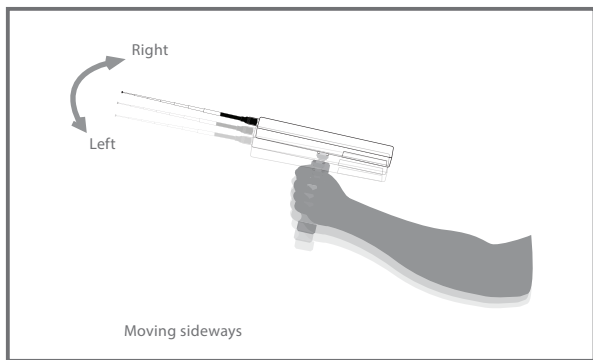


- | | |
|---------------------------|---------------------|
| 1 Antenna Jack | 5 Status indicator |
| 2 Power Button | 6 Target LEDs |
| 3 Target Selection Button | 7 Laser Pointer Out |
| 4 Laser Button | |

- ❖ The user must carry the device by grip horizontally slightly sloped towards ground as shown in the figure below



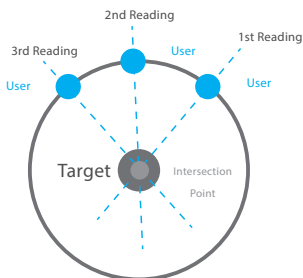
- ❖ Then stimulate the device's waves and output fields by moving the device right and left slowly then stop the device.



In the case of a located target , the device will receive signal and a reading that will divert the device from the normal track to another track which is the target point track, then the device will steady at the same direction ,in the meantime rotate fully around the direction that the device went toward until reaching the opposite and notice the track change once more and go toward the target.

then get 30 m sideways from the first reading point and stimulate the device's waves and steady the device and wait for the result if the target is legit the device will rotate towards the same point again therefore the target have been confirmed.

For more accurate reading and determining repeat the step from different points , and if all the tracks intersect in a point then it is the target point.



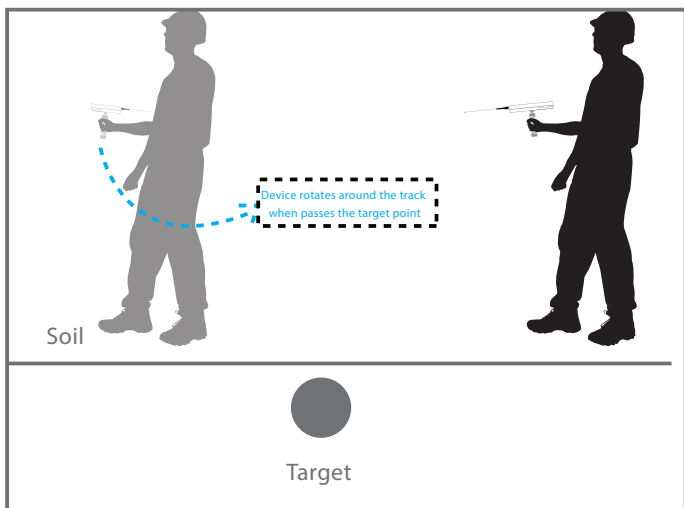
To estimate the target distance select different distance value and repeat the step above.

The successful steps indicates the approximate target distance.

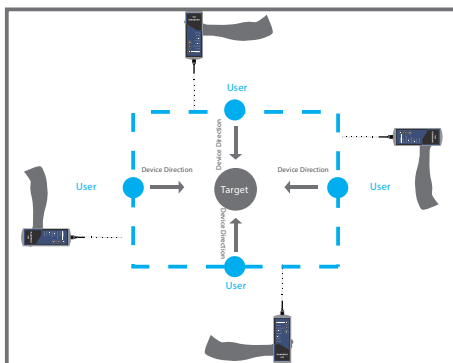
Repeat the process for accuracy.

How to Locate Target

- ❖ After ensuring multiple readings towards the target. Start walking in the same direction holding the device normally . until you reach the passing point you will notice that the device rotates around the normal track towards the point. Rotate with device slowly and start walking towards the target slowly until you reach the point where the device rotates right and left then you have located the target point.



- ❖ There is another way to locate the target point more accurately, (Square method) take 4 different readings for the target from 4 angles forming a square 3 m from target point the intersection point of the for readings is the target point.

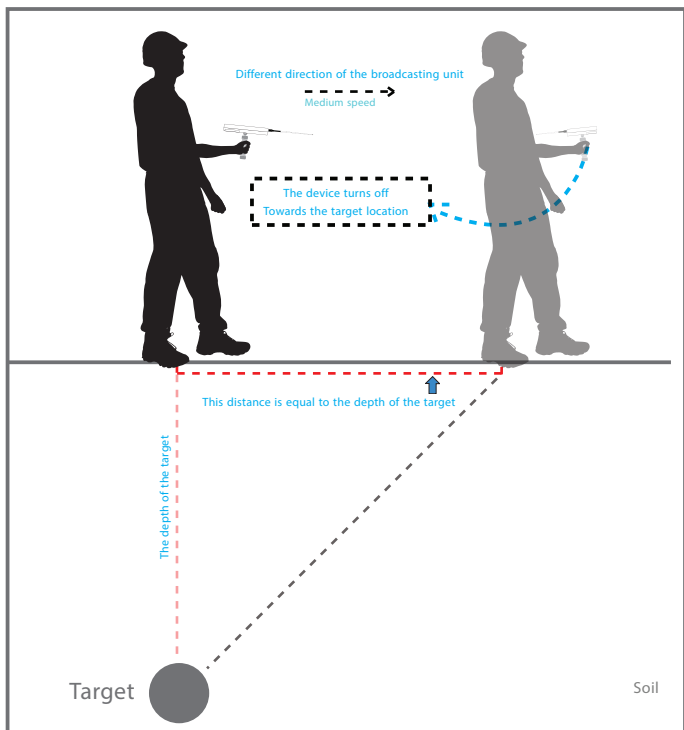


The user can see the approximate depth of the target by going back to the main menu, Select the search settings again, and changing the depth level through the depth list. For example, if the depth specified is the first time 5 meters we reduce the depth to 3 meters and enter the information, And we move away from the target location 20 meters and carry the device and wait for reading the target location, if there is a reading of the target site here we know that the depth may be between 3 meters, and we do this process to reduce the depth until we know the approximate depth of the target.

- Second method of depth determination:

After confirming the point of the target, we reduce the search distance to the lowest level and maintain the depth of the search to the highest level and complete the steps of work, and stand in the detection unit specified above the target directly and we go in a different direction of the transmission unit at medium speed until the unit circumvent the target location and measure the distance resulting from this The point to the target location is the depth of the target

How to Locate Target Depth



iON
Sense

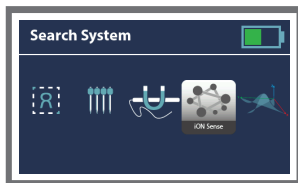
Verification Unit

This unit will detect the buried metals by sensing the ionic fields that formed around the metal in which the sensor will locate the metals location and beep in the area of the detected field.

This unit implement the ionic detection system. In which the device will identify the metals and burials ions underground that formed from being buried for a long period of time

Search Operation:	Metals and Burials Detection
Search System:	iON sense
Operating Processor:	Microcontroller
Processor Frequency:	20.000 MHz
Processing Type:	Digital Signal Processing (DSP)
Indicators:	Visual indicator (10 Bargraph LED) and Sound Indicator

If you selected the iON Sense search method, make sure that the Verification Unit is switched on and the indication LED is on



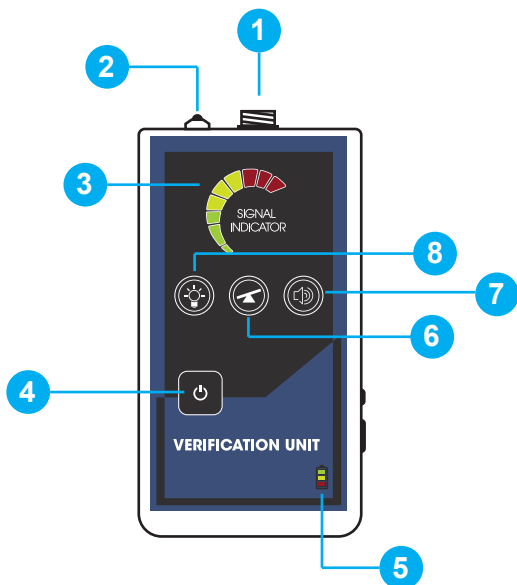
Select the target type for the search from the target menu then press "Enter".
Then press Start "Enter" again to confirm the target and start the search.



The "Verification Unit" will switch on and set to the selected target from the main unit wirelessly.

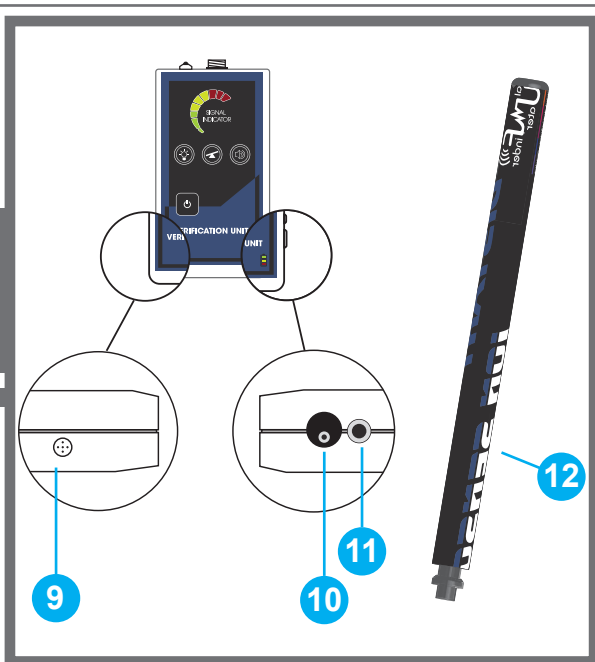
Note:

Make sure that the verification unit is switched on and within distance.



- 1 iON Sensor Connector
- 2 Flash LED
- 3 Visual Signal indicator
- 4 Power button
- 5 Battery indicator

- 6 Flash LED button
- 7 Volume button
- 8 Calibration button



- 9** Speaker out
- 10** Power Switch ON/OFF
- 11** DC in 5v-3A
- 12** iON Sensor: Connect to the iON Connector (1)



Power button: Press and hold to turn on the unit after switching the power switch ON.



LED flashlight button: press the button to turn the flashlight in the front of the unit for ease of use in night. Keep in mind that working with flashlight increases the power consumption and therefore less working hours.



Volume button: press the button to select the sound level



Ground calibration key: With this key, the user can adjust the unit to adapt to the terrain and environment in which the device operates. The device gives the normal and stable adjustment of the search tool for better results. Note: We may start searching in an area where the device is issuing a signal in general

We press the calibrate key once and wait for the signal to stabilize

If this continues to sound in any direction we press the key again until we get a stable result and then go to the search area to determine the targets.

There are three levels to adjust the calibration if the device is not calibrated. You are located in areas where there is high noise from high voltage, etc.

To use the Verification Unit ,First move away from suspected target location and calibrate the device by pressing the balance button, then start moving around the target location. The unit will react according to the target ionic field indicating sound and visual signals.

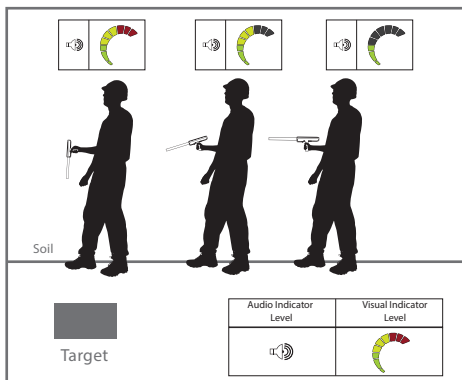
The signal will increase when the unit is near the target.

Note:

The ionic field intensity depends on the metal type and the period that been underground.

Note:

The approximate depth of the target can be determined by using this unit. After the target point is determined, direct the target to the target and walk in any direction until the acoustic indicator is disconnected. We measure the distance from this point to the target point, which is the approximate distance to the depth of the target.



Caution



- Charge the battery immediately after use.
- When the battery is full disconnect the charger.
- Only use the charge adapter that is attached with the product.
- Charge and store the unit away from flammable objects.
- Turn the unit off after use and don't leave it idle.

Battery Status while charging

Description	LED Indicator
Flashing Red: The battery is starting to charge in first stage	
The red indicator stops flashing and the yellow start to flash indicating the start of the second stage of the charging process	
The yellow indicator stops flashing and the green start to flash indicates the third and final stage of the charge process	
All lights on full battery charge achieved disconnect the charger	

Battery Status while working

Description	LED Indicator
Battery at 100%	
Battery at 50%	
Battery at 25%	
Flashing Red: The battery is low and the unit will shut-down automatically	

Charge Adapter for the Verification Unit :5V DC / 3-A 15W



Ground Sensor

The diagram shows a central rectangular box with a dark border containing the text "Ground Sensor" in blue. This box is positioned between two dark gray rectangular blocks. Below each gray block is a thin horizontal line. The entire diagram is enclosed within a large, light gray rectangular frame.

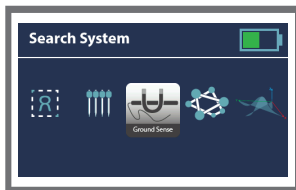
Ground Sensor System

The Ground Sensor System works on scanning the soil layers and identifying the contents by reading the magnetic fields to determine and locate the metals and voids underground.

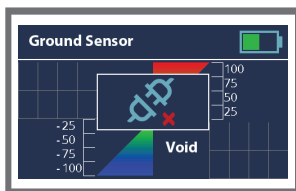
- ❖ A smart User Interface with all the needed data and ease of use about the search process
- ❖ Discrimination system to differentiate between metals and voids
- ❖ Waveform logging to keep track of the target size and place
- ❖ Advanced sensors to provide instant results in real-time
- ❖ Accurate obtaining to the target point with on screen display.

Search System:	Ground Sensor
Search Principle:	Sensing the magnetic fields of the target and display the results in real-time
Frequency:	Magnetic Measurement
Search Results:	Visual and audio signals with indicators in addition to waveform for logging

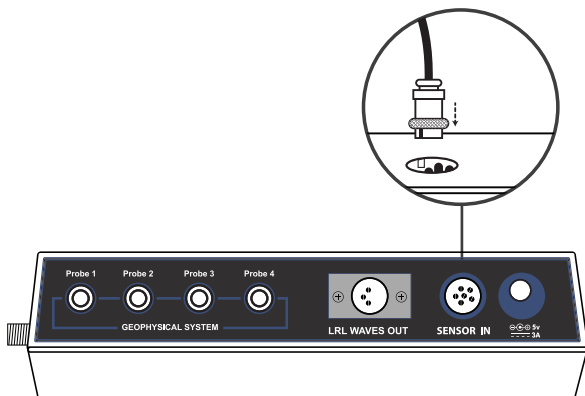
To start working with the Ground Sensor System go to main menu then select the system and press (ENTER) to go the system interface.



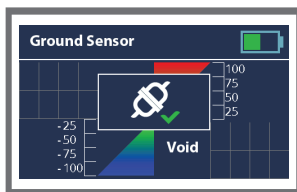
If the Ground Sensor is not connected, a notification will appear on the display indicating that the user must connect the Ground Sensor to continue working with the system.



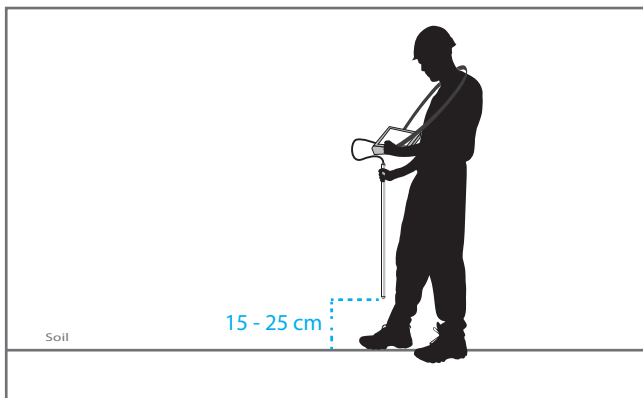
Connect the Ground Sensor plug to the sensor in jack in the back of the Main Unit as shown in the figure below.



A notification will appear on the display indicating that the Ground Sensor has been connected successfully. As shown in the figure below.



To start the scanning process put the carrying belt across the shoulders and hold the Ground Sensor 15-20 cm away from the earth surface perpendicularly to the earth.



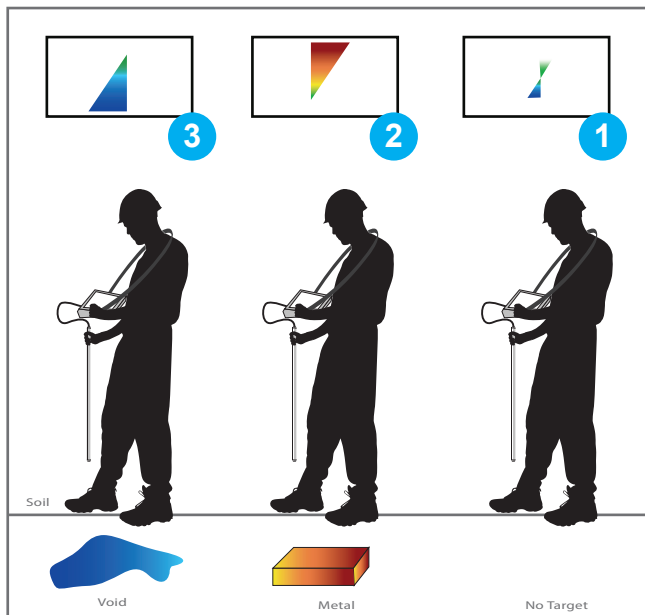
Before starting the user has to balance the device and adjust the sensitivity according to the ground by pressing ENTER or the Button on the top of the Ground Sensor to take a balancing measurement in a stable place unaffected.

The flux density is affected by the location of the search so in dense magnetic flux areas the readings will indicate false metal readings.

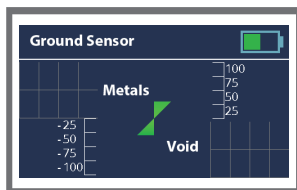
It might be necessary to take several balancing measures due to different soils and layers might have different flux fields.

The user has to walk toward the search area holding the Ground Sensor, After making a balance measurement.

The results of sensitivity will appear on the display in Real-time.

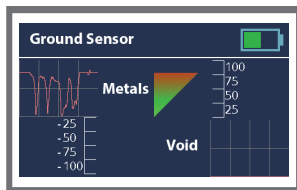


A stable indicator in the middle range indicates no targets in the search area.



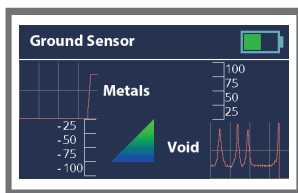
In case of metal target in the search are the indicator will show a high values in the high range of the display .

An increasement in the waveform above the midline will indicate the sensitivity of the target showing the contours of the target dimensions and size



In this case the existing target is void and the interactive indicator with high values of blue according to the received signals and the target size in the search area

A differential signals on the waveform will show the an increasment over the midline when cavity is sensed and the waveform would decrease below the midline after passing the target which will give the user an estimation of the cavity or void size and dimensions.



Geophysical

Geophysical Scan System

- ❖ This system scans the soil automatically and shows complete results about the targets immediately on the display.
- ❖ The system interface provides the user with the information about the search process and steps.
- ❖ Target discrimination feature with on screen display for the results and showing the information with up to six different target at the same scan process.
- ❖ Closing in feature to close in selected target after finishing the scanning process.
The system will guide the user to the target location accurately.
- ❖ Notification feature to assist the user in the search process in either a next step or an error with the search process.
- ❖ This system implements 4 electrical probes to cover large search area up to 1500 square meters with a scan result as fast as 3 minutes.
- ❖ Depth Detection feature to determine the depth of the founded target with a new accurate system.

- ❖ Double-check for the measuring process to give trusted result in real-time
- ❖ Accurate discrimination between target type and results
- ❖ Automatic system to check the wires connection constantly.

Search System:

Geophysical Scan

Search Principle:

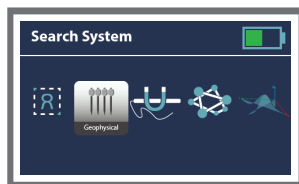
Scanning the ground layers and identifying the electrical resistivity and analyzing the results to locate target

Measurement Type:

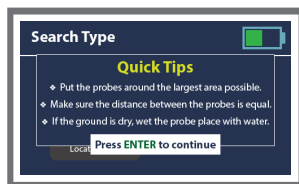
Measuring Electrical Resistance Impedence

Search Results:

Visual data with digital information about the target size and location



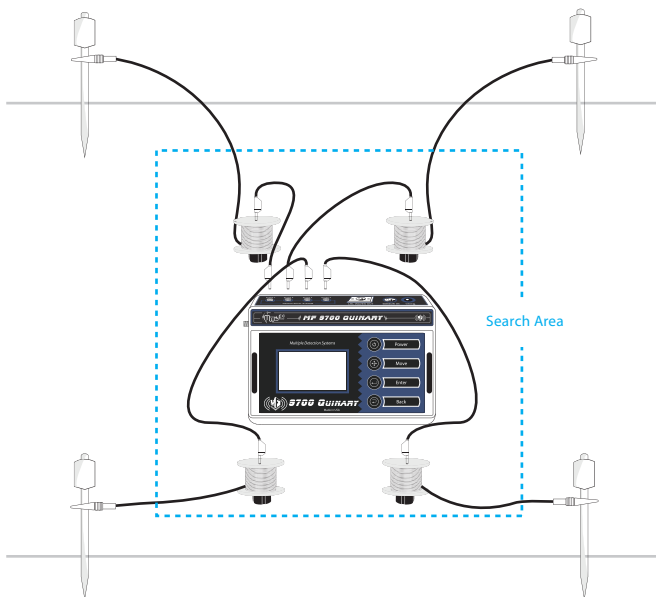
After selecting the Geophysical Search System the display will show a quick tips and advices about the search process. As shown below



Quick Tips

1- Put the probes around the largest area possible:

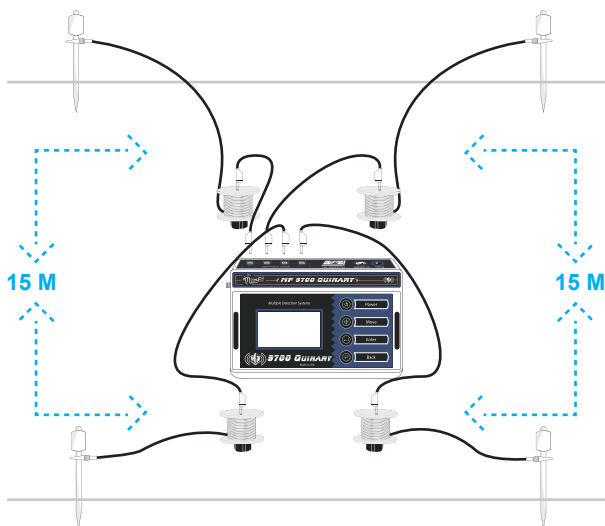
Which means if the search are is 5x5 meters start by putting the probes around an area bigger than the desired search area.



Connect the short wires to the reels and Main Unit , then connect the probes to the reels by the clips.

2- Make sure that the distance between the probes is equal

If -for example- the distance between probe 1 and 2 was 15 meters the other probes should be distanced at the same length which will form a square as shown in the figure below.



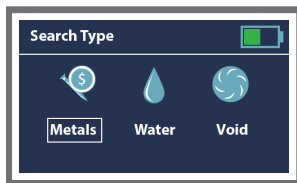
3- If the ground is dry, wet the probe place with water.

To ensure better conductivity and accurate results pour some water around the probe to enhance the signals.

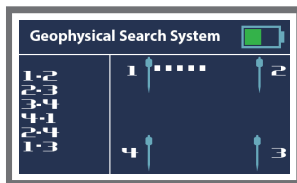
After following the instructions and connecting the probes press (Enter) to go to the Search Type menu.

Select the search type (Metal, Water or Void).

Select the type by pressing (Move) and confirm the selection by pressing (Enter).

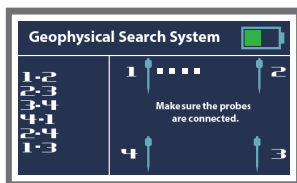


After selecting the search type the display will show the Geophysical Search System interface with four probes and the results on the right side for each reading of the probes. As shown in the figure below.



The device will start automatically the search after selecting the Search Type.
If the probes aren't connected properly to the device or there's disconnection in the reels, the device will show a message to check the probes for connection.
The active probes will have a connection that will show on the display to make the diagnostic process easier.

- ❖ In the example below the connection between the probes 1 and 2 is faulty and needs fixing.

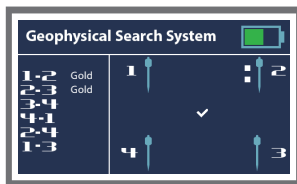


The search process will run in the order that's displayed on the right side of the screen.

After taking multiple measurements between every two probes the result will show beside the numbers

If there's no target between the probes the search will leave the space empty and proceed to the next probes.

As shown in the figure below.



An example of the search process

After finishing the process mentioned earlier the display will show the result of the search according to the position of the probes.

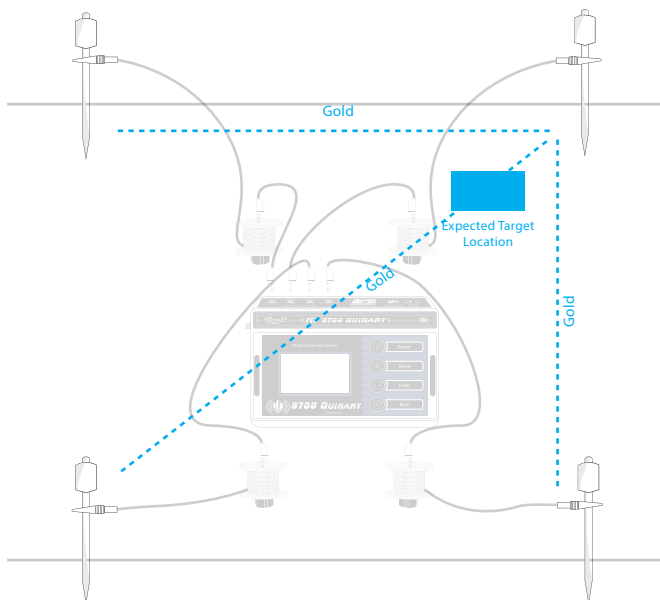
Continuing the search options selected earlier the search results are:

By the reading the gold is located between the probes(1-2 / 2-3 / 2-4) which triangulate the location of the target
As shown in the figure.

Note:

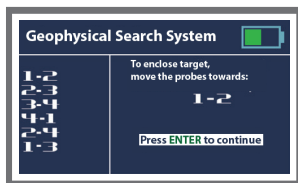
In the search process the device will notify the user of any errors or results:

- A message with audio signal notifying that the probes are not connected properly
- Audio signal notifying the user that the search process moved to another probes
- Audio signal for notifying the end of the search



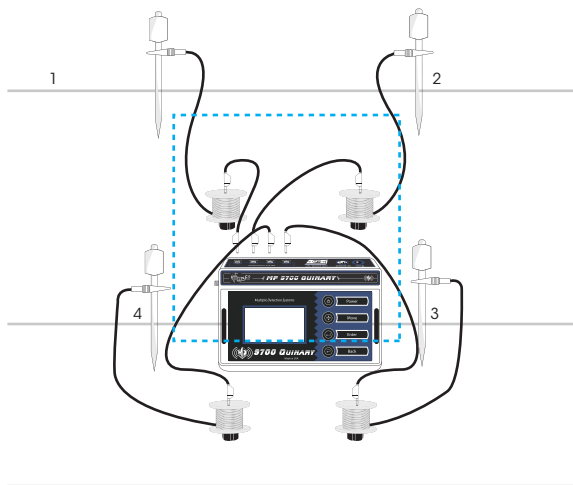
After analyzing the measurements and triangulating the target , the device will show a messege to select the target for closing.

Select the target by pressing (Move) and confirm with (Enter) to continue.



Closing the target according to the readings from probes 1-2

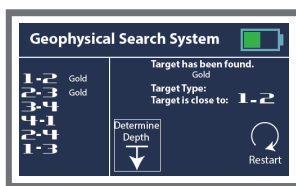
A message will show that moving the other probes towards the selected target for closing.



After moving the probes closer towards the probes (1-2) and pressing (Enter) the device will restart the scan process to confirm the target.

After locating the target between the probes and closing on it a message will appear on the device indicating the target type and closest probes.

As shown in the figure below.



After determining the target type and location the device will show two options on the display

- The first option is to go back to the Main Menu. To go to Main Menu select exit by pressing (Move) and confirm with (Enter).
- The Second option is Depth Detection for the target under the ground.

When the Depth Detection is selected a message will appear to connect the probes (1-2) to start the Depth Detection Process.

Press (Enter) to proceed.

Note:

Depth Detection process only uses the probes(1-2).

There's no need for the other probes for the depth process.

Depth Detection

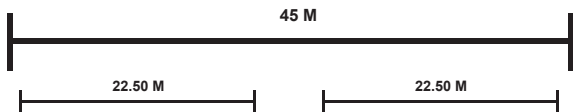
- 45 m ✓
- 40 m ✓
- 30 m ✓
- >25 m ✓
- 15 m
- 7 m
- 5 m
- 3 m



Depth Detection

After connecting probes (1-2) to the device notice the list on the left side which consist of predetermined distances to compare the results to.

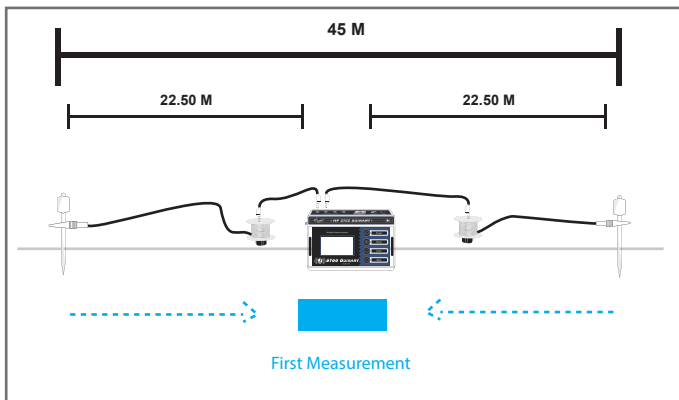
The distances shown on the display indicate the complete distance between the probes .



The Interface will automatically prompt the next step on display after completing the previous one.



Move the Probes closer then press (ENTER)



40 M

20 M

20 M



Second Measurement

30 M

15 M

15 M



Third Measurement

25 M

12.5 M

12.5 M



Fourth Measurement

15 M

7.5 M

7.5 M



Fifth Measurement

7 M

3.5 M

3.5 M



Sixth Measurement

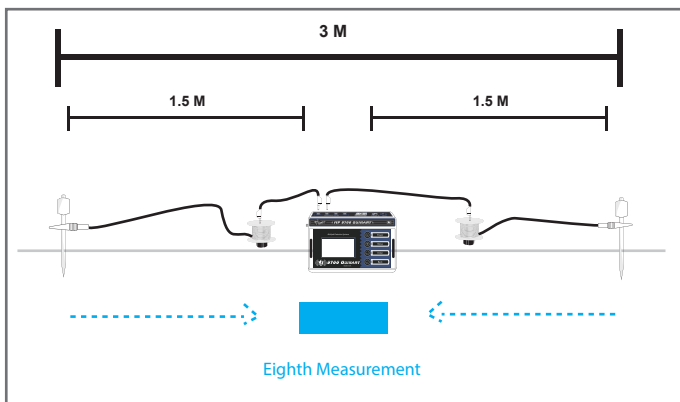
5 M

2.5 M

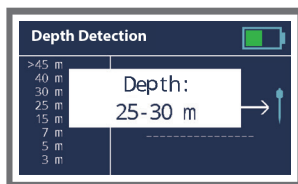
2.5 M



Seventh Measurement



When the depth process is done a message will be shown on the display indicating the result of the process.





Ground Scan

Ground Scan System

- ❖ This system will measure the intensity of the earth magnetic fields and analyzes it to detect metals and burials underground and other mining purposes.

By measuring and scanning the data from the radio sensors and the electro-magnetic inductors using multiple frequencies such as VHF and UHF to ensure a wide range of measurement.

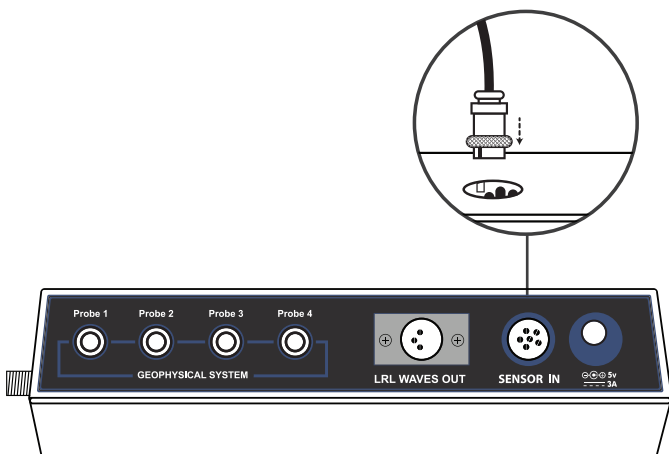
- ❖ Ground Scan System measures and records the reflection time and the waves amplitude to detect the location of the objects, metals, underground burials and cavities.

These readings will be visualized by a grid illustration with the intensities shown in different colors making the shape of the object.

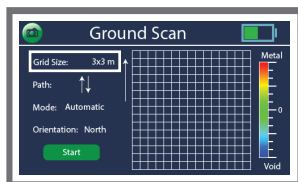
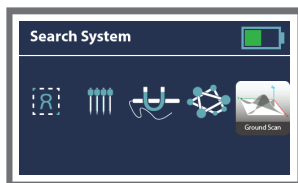
This system is usually used with pre-known archeologic sites.

Setup

Connect the Ground Sensor plug to the sensor in jack in the back of the Main Unit as shown in the figure below.



After selecting the Ground Scan search system as shown below the device will go into the interface for the Ground System search to start the process.



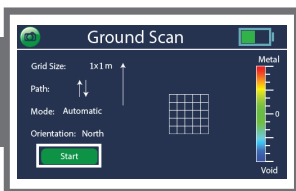
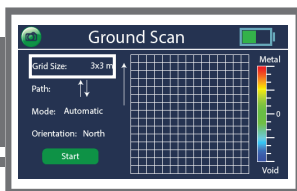
Before starting select the search parameters by pressing(MOVE) and change the values by pressing (ENTER)

Scan Parameters

Grid Size:

The system uses a grid of squares to determine the target.

There are three grid sizes, 1x1 m, 2x2 m and 3x3 m keep in mind that the overall search area is divided into steps for the grid.



Path:

This option is for the search process path two available settings:

One direction: in which the user will have to start searching from the bottom of the grid and after the column is finished the next column also starts from the bottom of the grid.

Two direction: in which the search process starts from the bottom of the grid then when the first column is finished the next one starts from the top of the grid.

Mode:

This option selects the readings acquiring mode:

Automatic: In this mode, the device will acquire the measurement without the need to press the button every time. The device will make a sound indicating that a measurement is done and the user will move to the next step.

Manual: The user will have to press the button on the top of Ground Sensor or Enter for every step to take a measurement.

Note:

Keep in mind that the default size for the step is 20 centimeters in both modes.

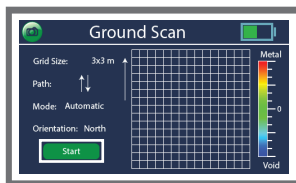
Orientation:

The facing direction of the start point.

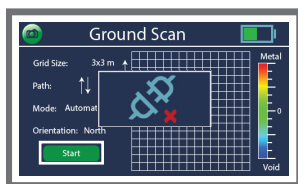
Note:

It's recommended to start the scan from North to South.

After selecting the required search parameters Select START on display and press ENTER.

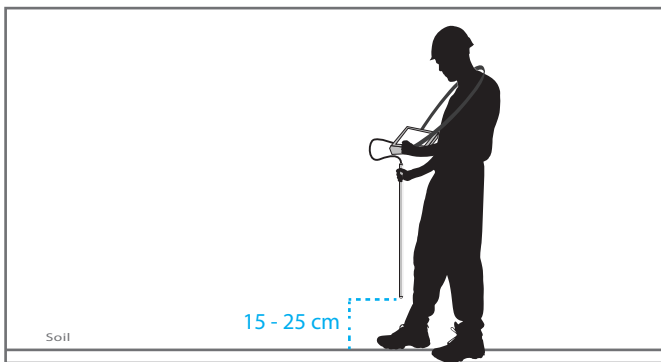


When starting the search make sure that the Ground Sensor is connected to avoid the error message, as shown below.



Starting up

To start the scanning process put the carrying belt across the shoulders and hold the Ground Sensor 15-20 cm away from the earth surface perpendicularly to the earth.



Note:

Before starting the user has to balance the device and adjust the sensitivity according to the ground by pressing ENTER or the Button on the top of the Ground Sensor to take a balancing measurement in a stable place unaffected.

The flux density is affected by the location of the search so in dense magnetic flux areas the readings will indicate a false metal readings.

It might be necessary to take several balancing measures due to different soils and layers might have different flux fields.

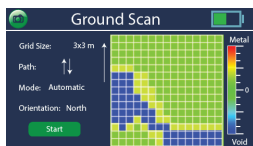
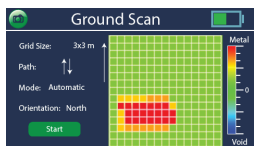
When starting the search process the user has to scan according to the selected search parameters in 20 cm steps.

After the balancing measurement is done the scanning process will show the result on display instantly, as shown below.



Soil





Soil

Tips for using the Ground Scan

Make sure that the Ground Sensor is Connected firmly to the Main Unit before starting the Scan

While moving to take scan readings don't rotate the Ground Sensor .

The sensor must be facing the same direction on the start of the scan.



❖ It's recommended to start the scan from North to South.

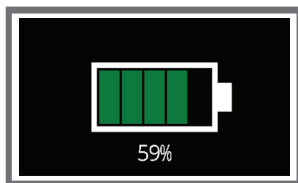
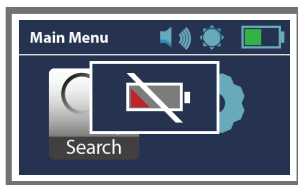
The scan step size is 20 cm in all directions and modes

Notes:

-The device will make a beeping sound when the battery is full and the charging is done, so disconnect the charger when the notification is heard.

-An indicator will show the charging progress in the upper corner while the device is working.

-To ensure the performance of the device is kept in best state, Turn the device off and remove any batteries before storing.



[illegible]



United States of America - illinois

www.mwf-usa.com
info@mwf-usa.com
9602 364 (708) +1

SHOP DETECTORS

TEL : +1 206-401-9788

WEB : <https://shopdetectors.com/>

EMAIL : contact@shopdetectors.com

Turkey - istanbul

www.mwf-metaldetectors.com
info@mwf-metaldetectors.com
0946 222 (212) +90
0947 222 (212) +90